



Gear motors RD50/70/85-HD

Compact actuators for high precision and backlash-free drives in industry and robotics

The geared motors of the RD-HD series are high-torque and high-precision servo solutions with hollow-shaft for low-voltage applications. The technology from Harmonic Drive uniquely combines highest precision and zero backlash in a compact lightweight design. RoboDrive technology allows Harmonic Drive gears to be operated at their peak performance.

Due to the outstanding dynamics of the RoboDrive motors and the very low gear elasticity and inertia it is possible to precisely control the powertrain. This allows the geared motors RD-HD to be used successfully in robotics, handling and automation, medical and optical applications.

On request other sizes and types of Harmonic Drive gears are delivered with matching motors.







Key features:

- Hollow-shaft with protective tube
- Industry-leading power density
- Excellent torque density and positioning accuracy
- Absolute encoder with high resolution
- Very compact and lightweight design

Basic data

	RD50x08-HD	RD70x10-HD	RD85x13-HD
Power P [W]	155	270	430
Rated output torque T_r [Nm]	7.8	40.0	67.0
Peak output torque T _{max} [Nm]	28	92	176
Collision torque T _{col} [Nm]	54	147	304
Output speed n _{max} * at U _r [rpm]	55	22	18
Gear ratio **	1:100	1:160	1:160
Diameter D [mm]	61	80	96
Length L [mm]	54.3	63.5	70.3
Weight m [g]	890	2600	3650

^{*}Theoretical no-load rotation speeds at $U_{j} = 48 \text{ V}$. Variations can arise from operation with different inverters. Higher rotation speeds or change of the voltage level can be achieved by adapting the interconnection scheme.

^{**} Other gear ratios are available on request.

Electrical data

	RD50x08-HD	RD70x10-HD	RD85x13-HD
Rated voltage U _r [V]	48	48	48
Rated current I _r [A]	3.26	3.37	4.60
Torque constant k _T [Nm/A]	0.057	0.106	0.13
Terminal resistance R_{TT} [m Ω]	552	470	210
Terminal inductance L _{ττ} [μH]	720	800	470
Number of pole pairs	10	10	10
Sensor type*	Magnetic encoder, BiSS-C differential, accuracy \pm 0.1°, supply voltage $U_{dd} = 5 \text{ V}$		
Position resolution (drive side)	100,000 inc/rev	160,000 inc/rev	200,000 inc/rev

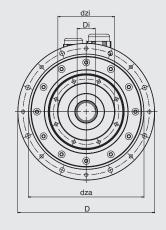
All data relate to star-serial interconnection at U_i = 48 V. The voltage can be adapted on request. * SSI, SPI, PWM, I2C, asynchronous serial communication interfaces can be realized on request.

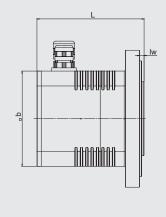
Gear data

	RD50x08-HD	RD70x10-HD	RD85x13-HD
Туре	CPL-14A-100-2A	CPL-20A-160-2A	CPL-25A-160-2A
Torsional stiffness [Nm/arcmin]	1.0	8.4	16.6
Lost motion [arcmin]	< 1	< 1	< 1
Max. tilting torque [Nm]	205	230	277

Dimensions

	RD50x08-HD	RD70x10-HD	RD85x13-HD
Diameter D [mm]	97	128	141
Motor length L [mm]	77.6	99.8	111.3
Edge length b [mm]	66	89	103.5
Centering shaft diameter dzi [mm]	35 H6	53 H6	58 H7
Hollow-shaft diameter Di [mm]	10.5	17	21
Shaft length lw [mm]	4.2	4.2	5
Centering diameter dza [mm]	83 h6	108 h6	118 h6





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